

Learning Causal Effects via Weighted Empirical Risk Minimization

Yonghan Jung

PURDUE
UNIVERSITY



Jin Tian

IOWA STATE
UNIVERSITY



Elias Bareinboim

 **COLUMBIA UNIVERSITY**
IN THE CITY OF NEW YORK

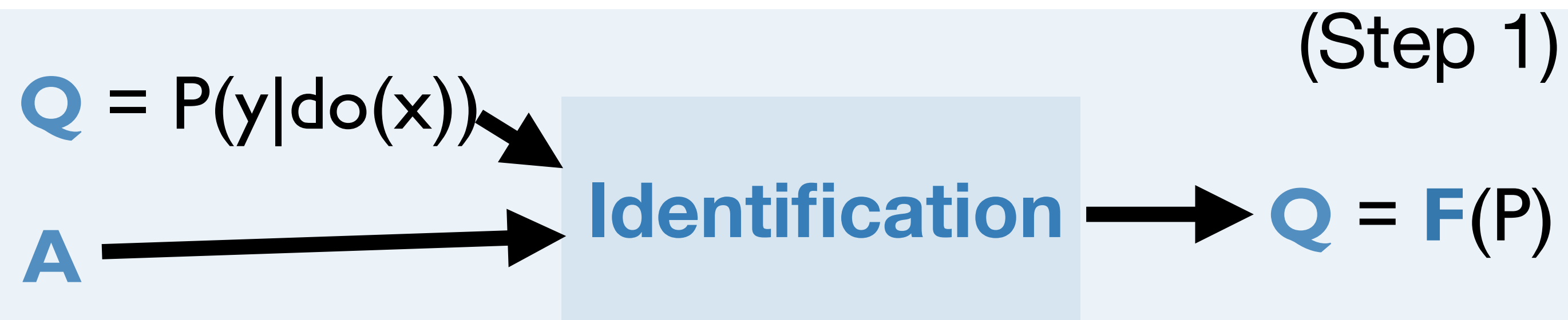


Learning causal effect: 2-step procedures

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Step 1. (Identification)

Represent the causal query $Q=P(y|\text{do}(x))$ as a function of P (i.e., $Q=F(P)$) from causal assumption A .



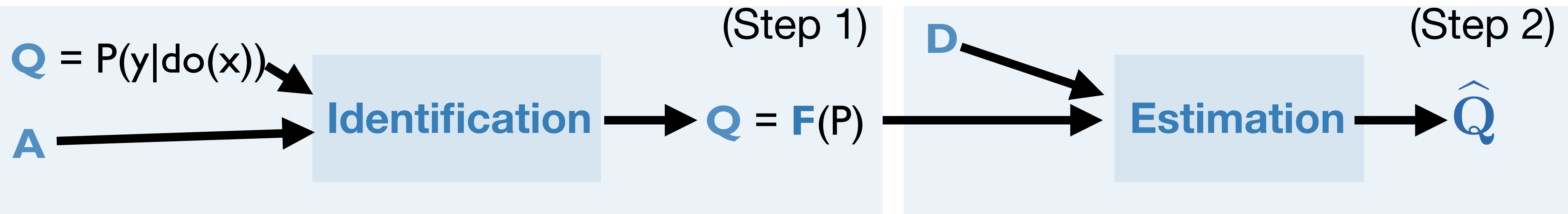
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Step 2. (Estimation)

Estimate the identified estimand $Q=F(P)$ from finite samples D

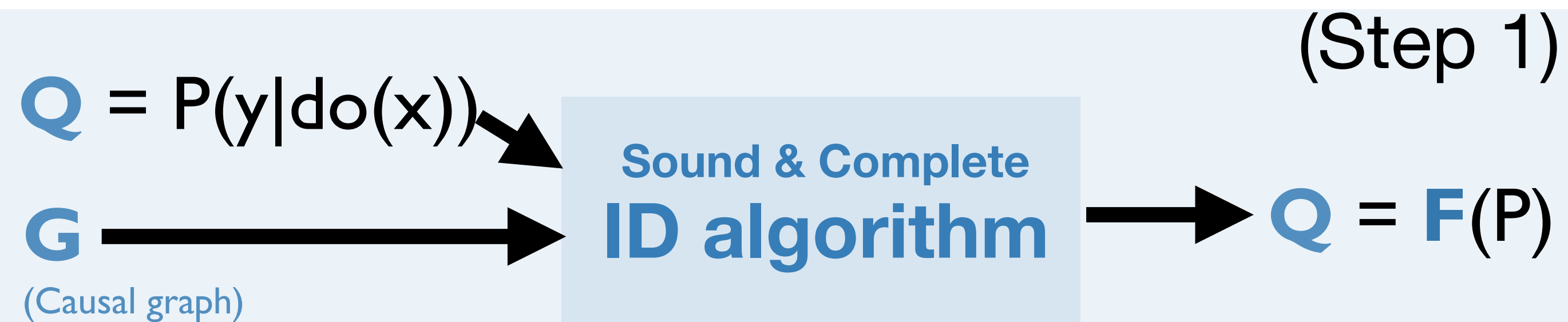


Current status of causal inference

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Strength

- We have a sound and complete identification algorithm — A procedure for determining whether a causal query Q is could be represented as a functional of P (i.e., $Q=F(P)$) from the causal assumption.



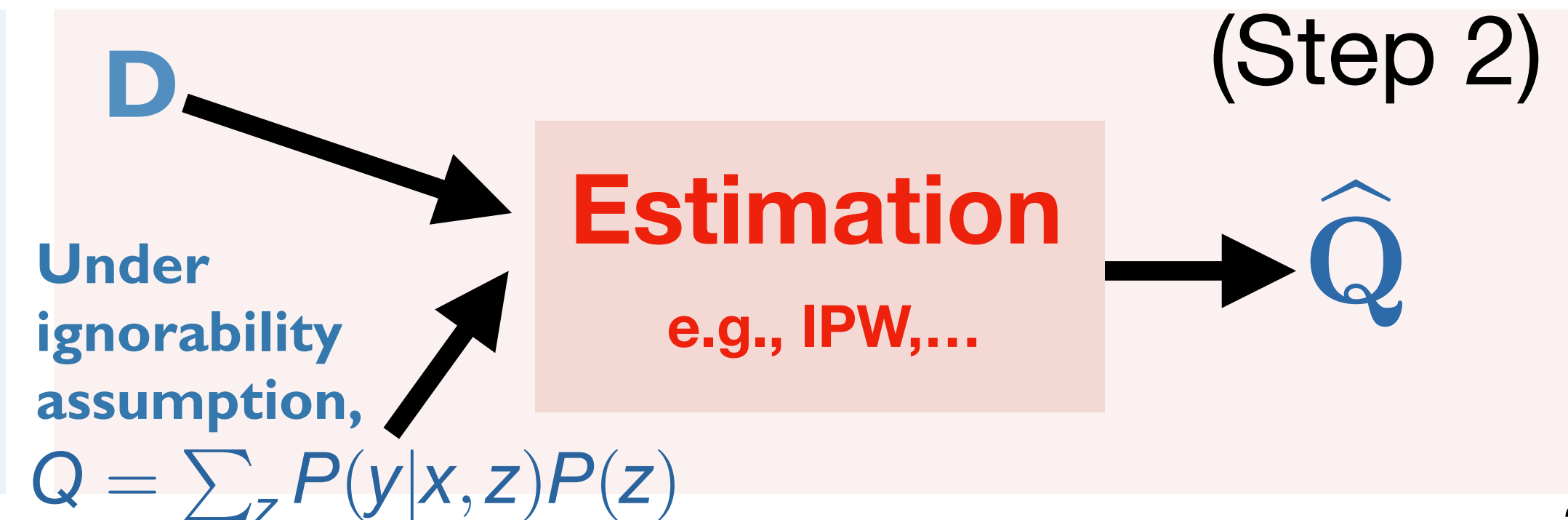
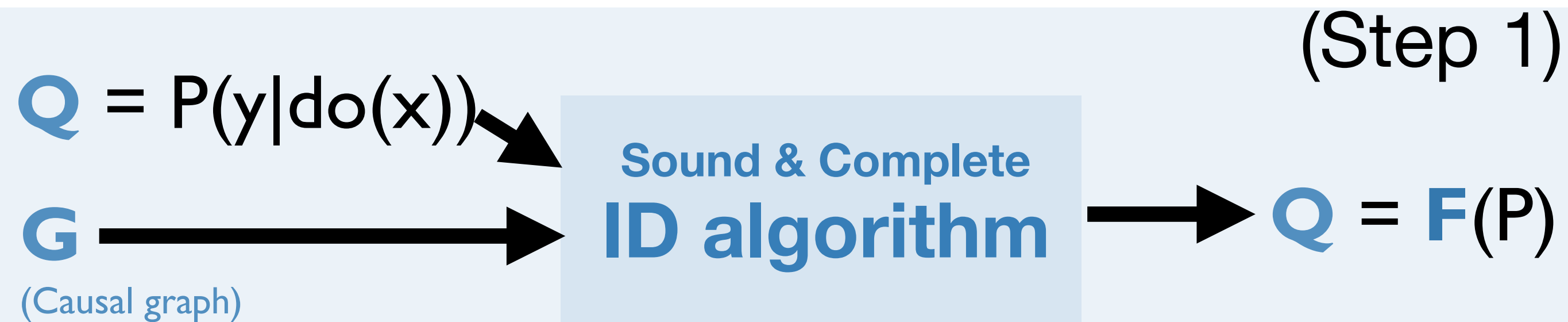
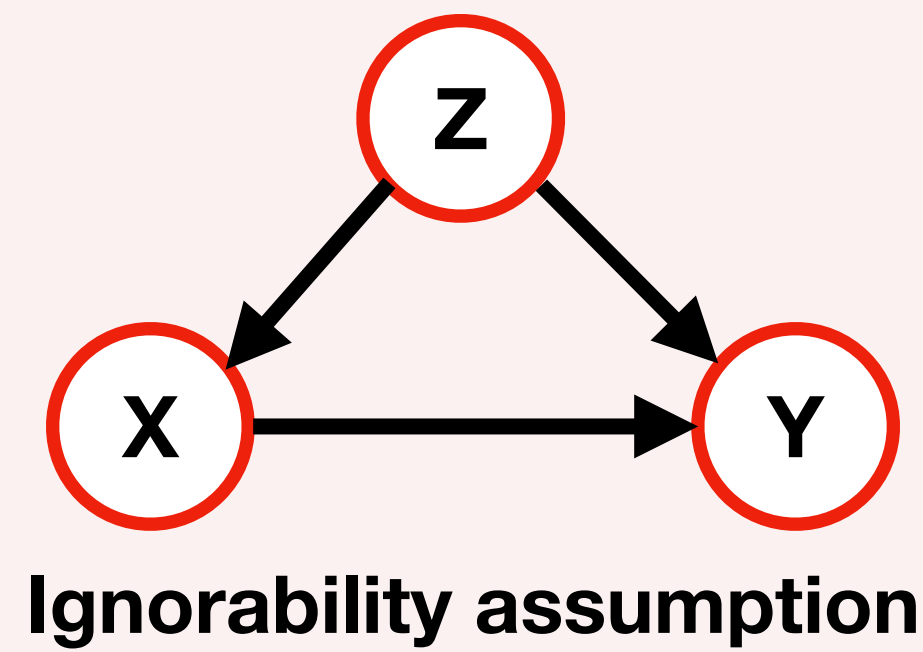
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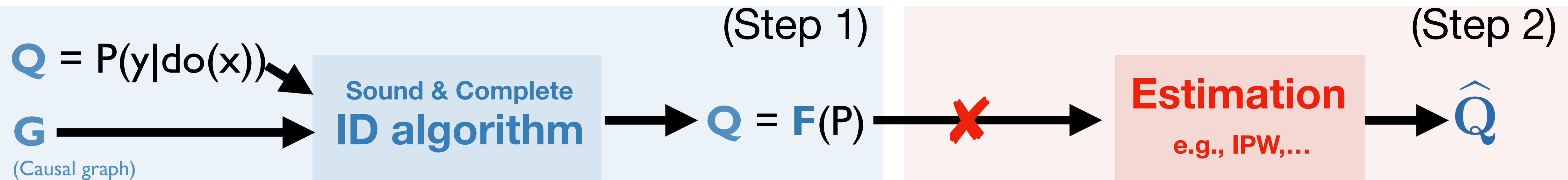
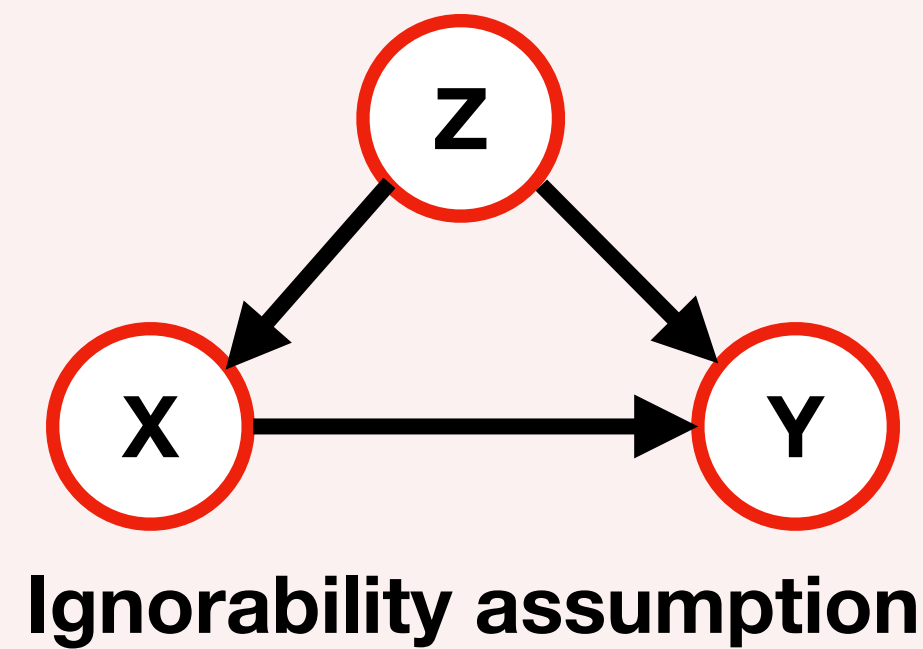
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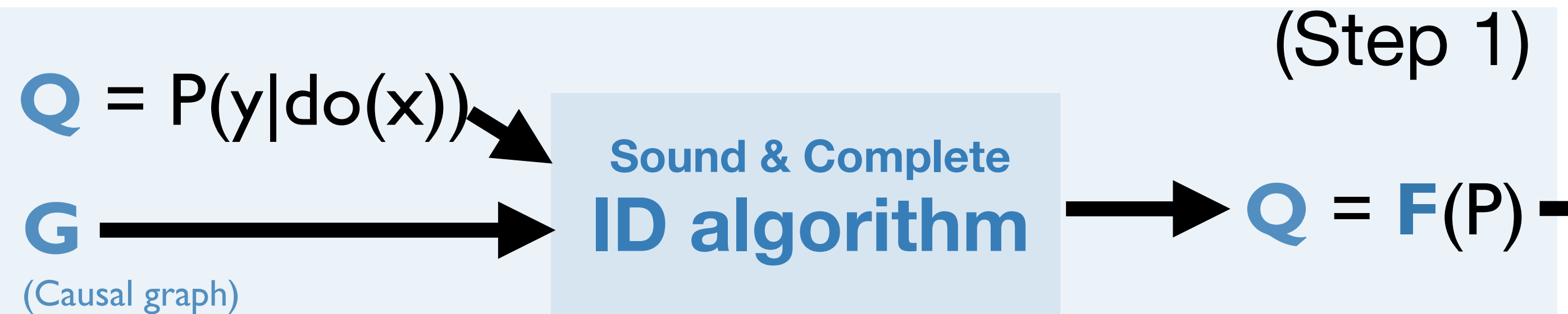
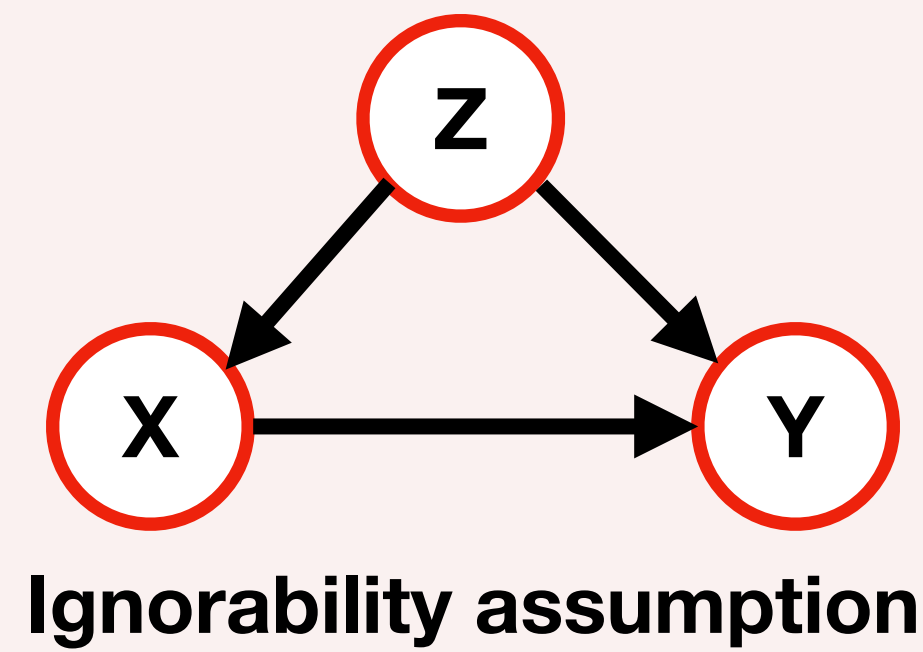
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Learning causal effect: (Weighted) ERM

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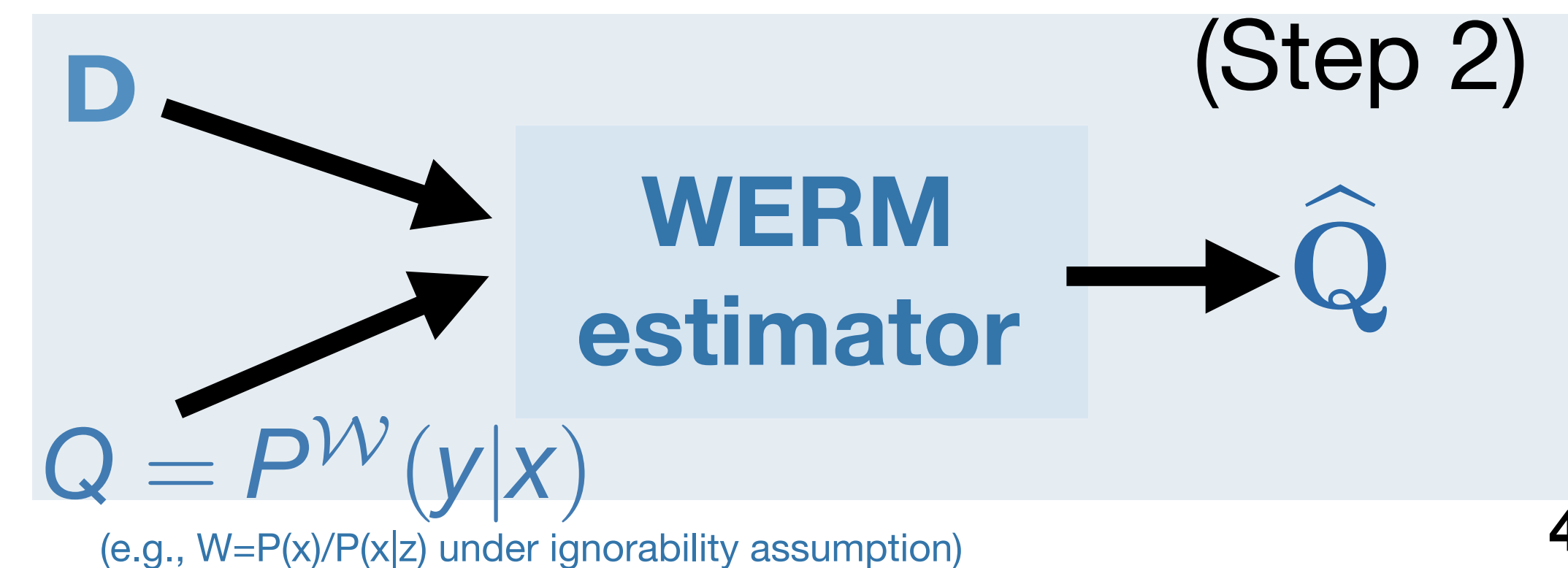
- When $Q=F(P)$ is given as ***weighed distribution*** (e.g., *inverse probability weights (IPW) or importance sampling*), then the empirical risk minimization (ERM) based estimators have been established.

Counterfactual Risk Minimization

Swaminathan and Joachims (2015)

Re-weighted Risk Minimization

Johansson (2018, 2020)



Learning causal effect: (Weighted) ERM

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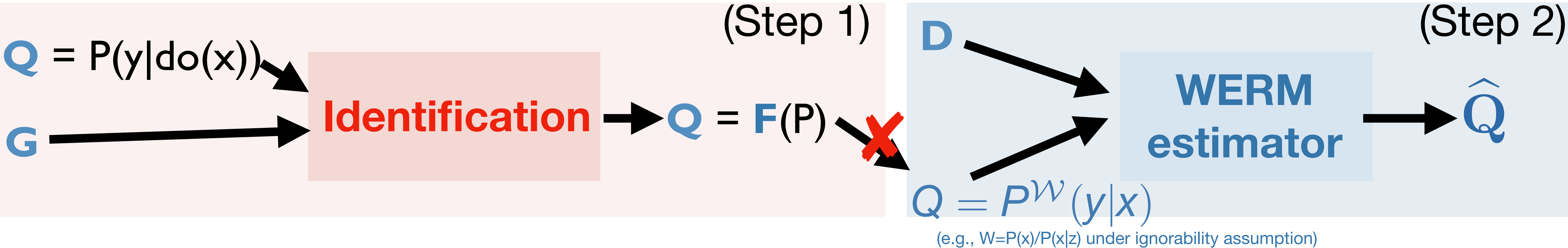
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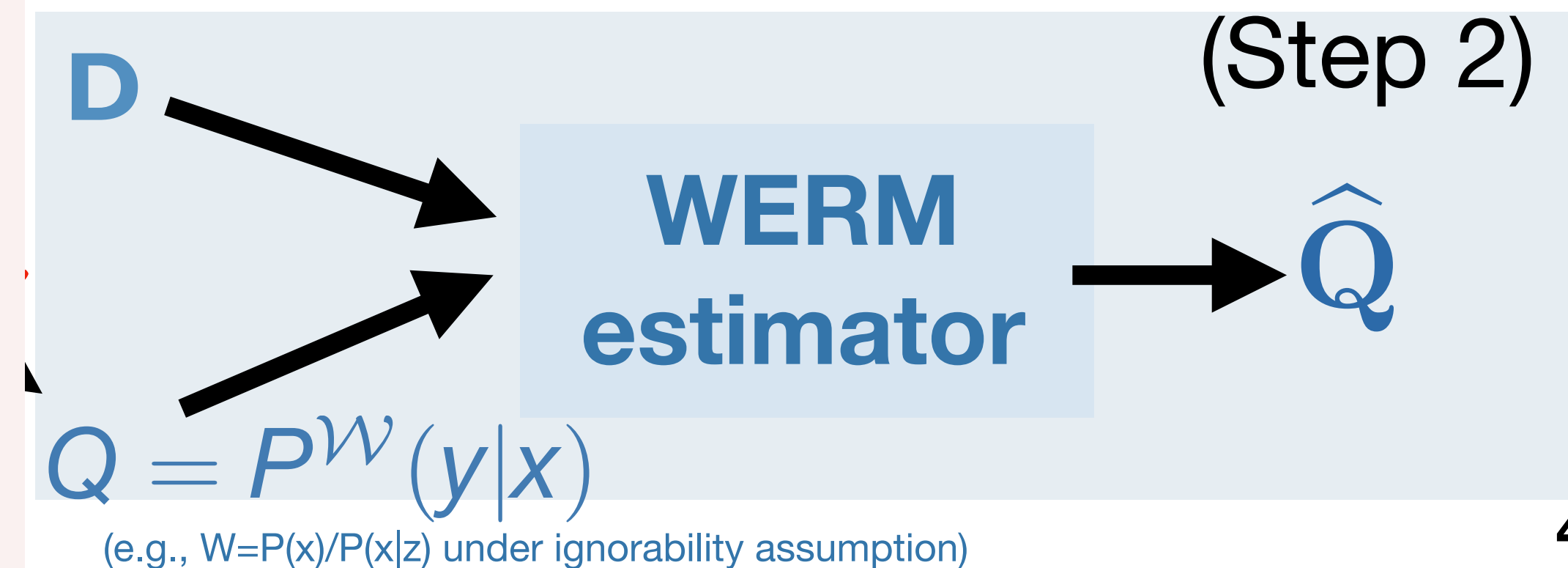
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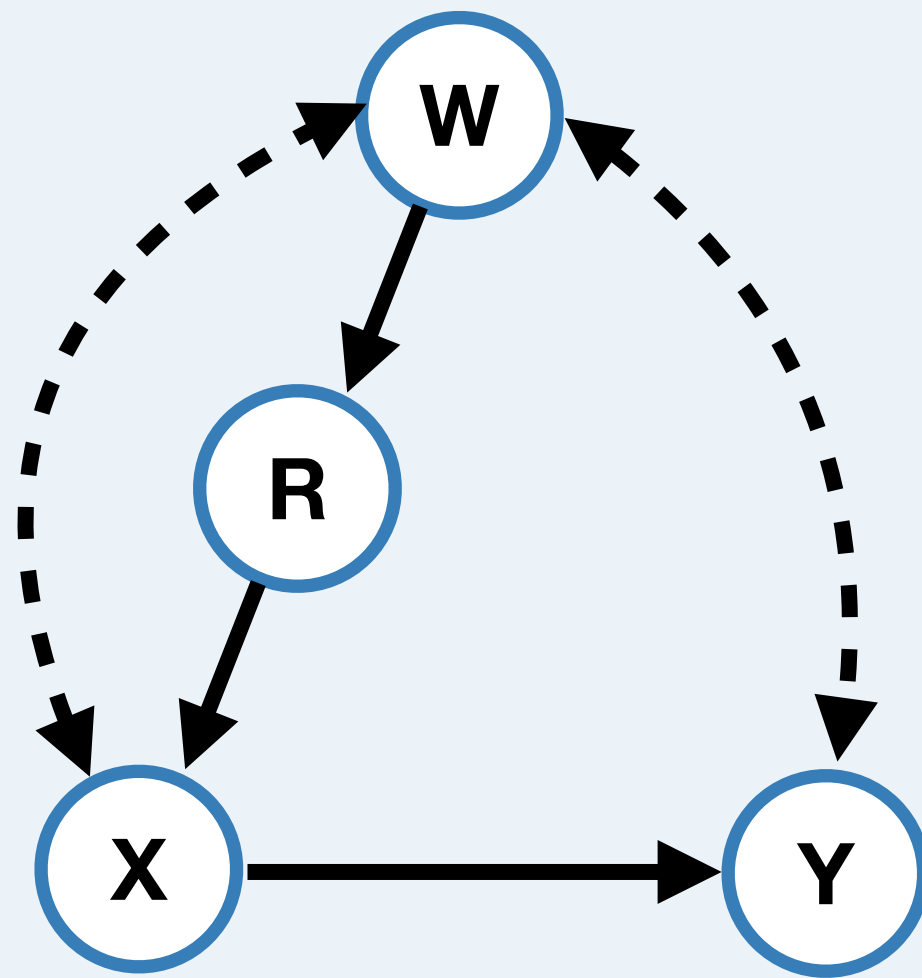
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Connection b/w non-igno. and WERM

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Practical Scenario on Non-igno. case (Example 1)



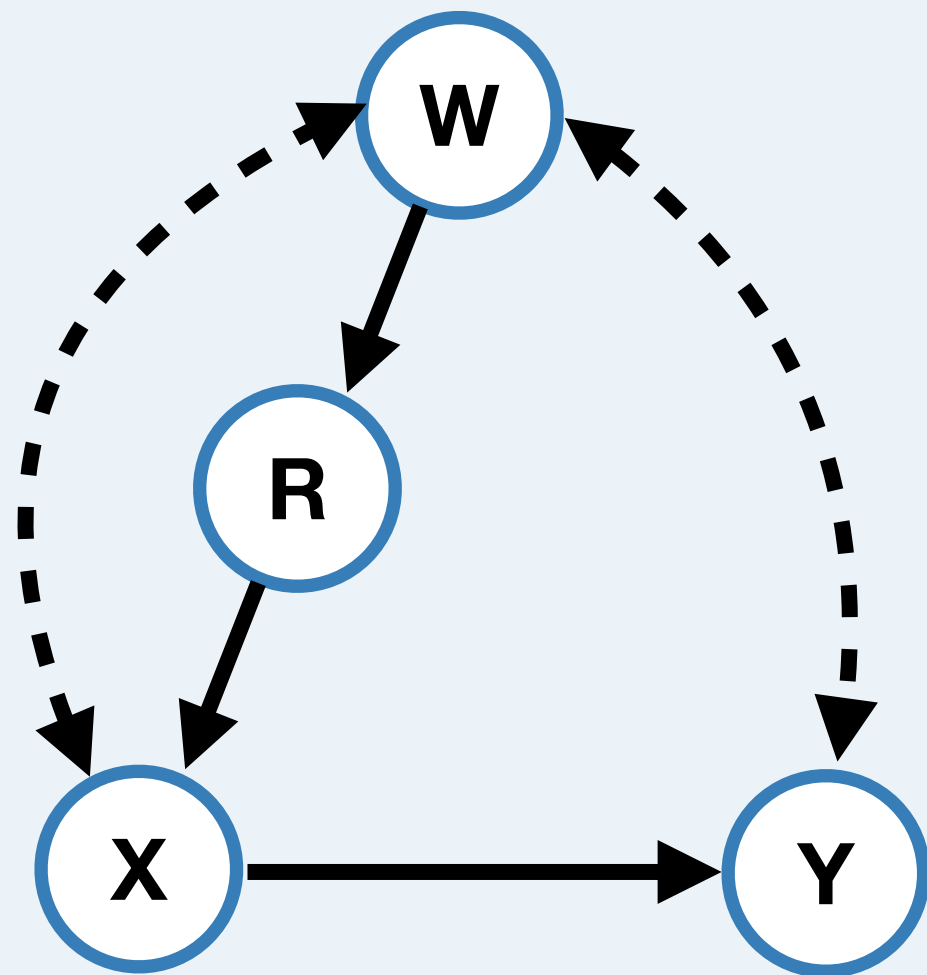
$$P(y|do(x)) = \frac{\sum_w P(y,x|r,w)P(w)}{\sum_w P(x|r,w)P(w)}$$

- The causal effect is identifiable, but the estimand is not a typical input for the WERM estimator.



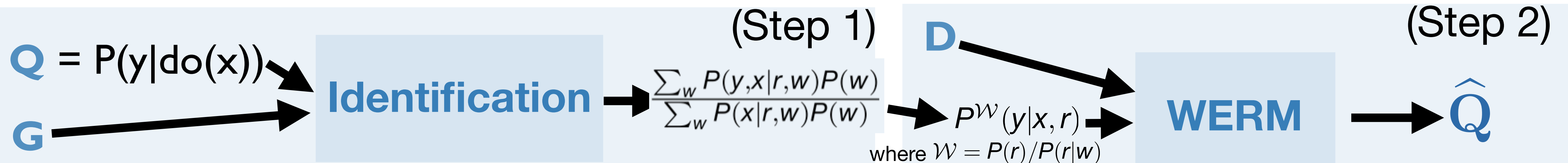
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Practical Scenario on Non-igno. case (Example 1)



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- The causal effect is identifiable, but the estimand is not a typical input for the WERM estimator.
- However, we can represent the query $Q=P(y|do(x))$ as a weighted distribution
- Taking $W=P(r)/P(r|w)$. Then,
$$P(y|do(x)) = P^{\mathcal{W}}(y|x, r)$$



End-to-end solution to causal inference

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Contribution Filling the bridge between causal effect identification and the estimation

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Identification

$$(W^*, R) = \text{wID}(Q, P, G)$$

(Algo. I)

such that

$$P(y|\text{do}(x)) = P^{W^*}(y|r)$$

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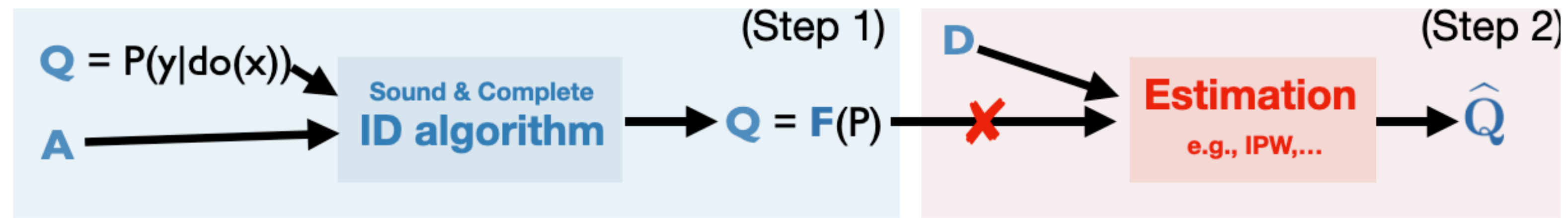
Estimation (Sec. 4)

- Generalization bound (Prop. 1)
- Structural Risk Minimization (Thm. 2)

Summary

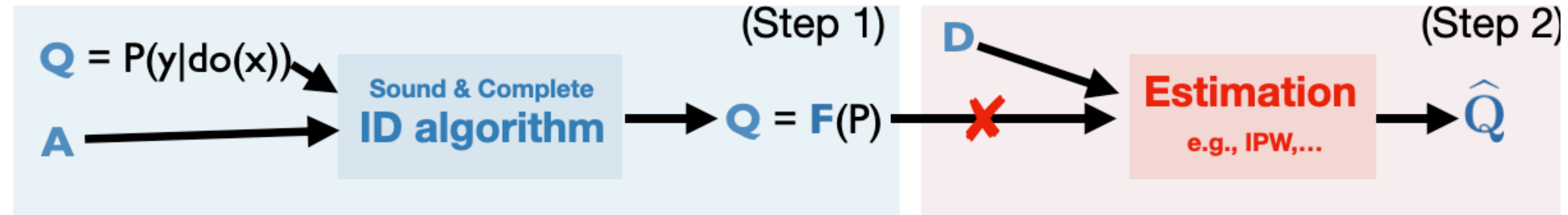
Summary

- A gap b/w causal effect *Identification* and *estimation*.

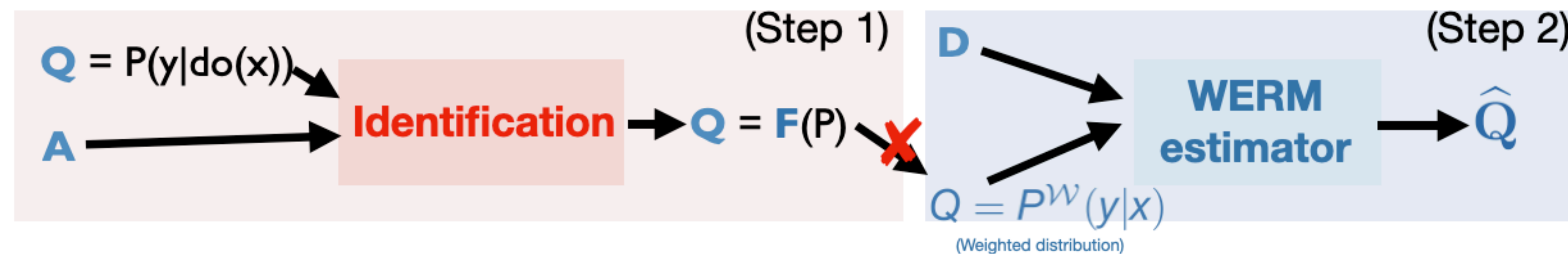


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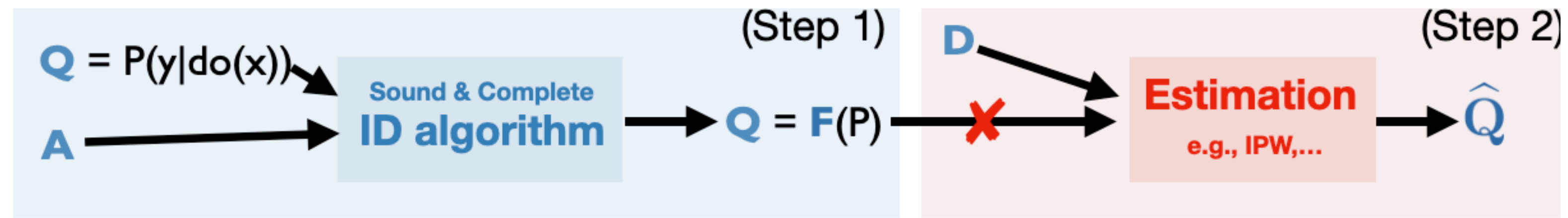


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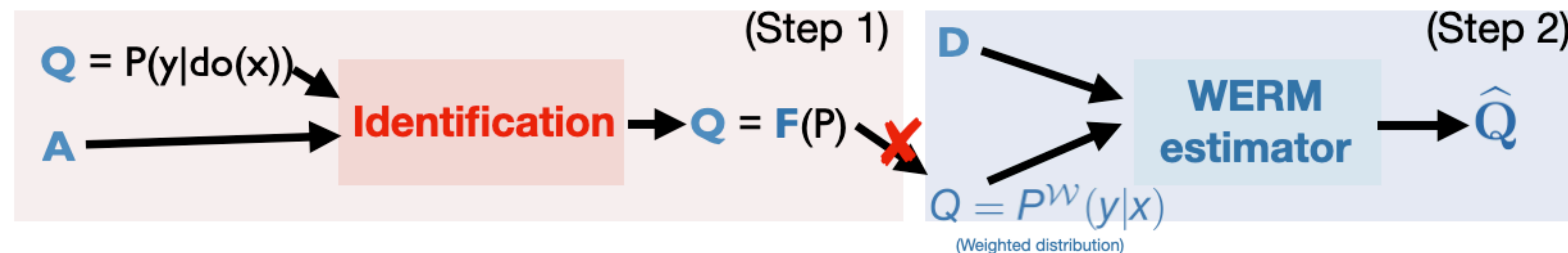


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- A gap b/w ERM based estimators and the *causal inference*.



- We fill the gap between the causal inference and the ERM based estimation.

